

Simple Stream Specifications with Undecidable Productivity

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$$c \rightarrow 0 : f(c) \rightarrow 0 : f(0 : f(c)) \rightarrow 0 : f(0 : f(0 : f(c)))$$

Limits of decidability

Stream differential equations(C.Kupke, M.Niqui, J.Rutten, 2011)

$$i(\sigma, \tau) := \sigma \quad d(a1.a2) := \text{zip}(y2, x1)$$

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Lazy Stream Specification (J.Endrullis, C.Grabmayer, D.Hendriks, 2009)

$M_P \rightarrow \text{zip}_d(T_1, \dots, T_d)$, where:

$$T_n = \begin{cases} \text{mod}_{p'_n}(\text{tail}^{b_{n1}}(M_P)), & \text{if } p'_n \text{ is defined,} \\ \bullet : \text{mod}_d(\text{tail}^{n-1}(M_P)), & \text{if } p'_n \text{ is undefined} \end{cases}$$

$$\text{head}(x : \sigma) \rightarrow x \quad \text{tail}(x : \sigma) \rightarrow \sigma$$

$$\text{mod}_k(\sigma) \rightarrow \text{head}(\sigma) : \text{mod}_k(\text{tail}_k(\sigma))$$

$$\text{zip}_d(\sigma_1, \sigma_2, \dots, \sigma_d) \rightarrow \text{head}(\sigma_1) : \text{zip}_d(\sigma_2, \dots, \sigma_d, \text{tail}(\sigma_1))$$

Queue machines

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- Our variant:

$$\delta_0 : Q \rightarrow A \times Q$$

$$\delta_1 : Q \times A \rightarrow A \times Q$$

$$\delta_2 : Q \times A^2 \rightarrow A \times Q$$

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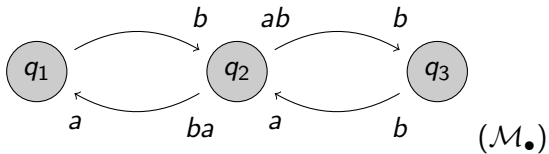
$$\delta_0 : Q \rightarrow A \times Q$$

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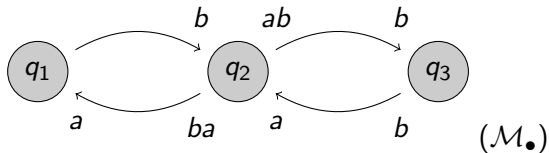
$$\delta_2 : Q \times A^2 \rightarrow A \times Q$$

- Halts by taking 2 letters where there is 1.
- **Fact:** halting problem is undecidable

Example

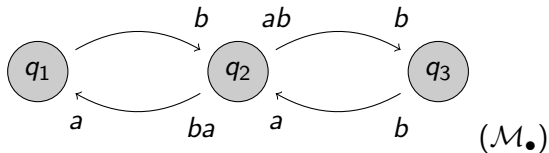


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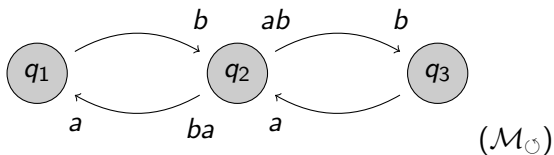


$(q_1, a) \rightarrow_{\mathcal{M}_\bullet} (q_2, ab) \rightarrow_{\mathcal{M}_\bullet} (q_3, b) \rightarrow_{\mathcal{M}_\bullet} (q_2, a)$

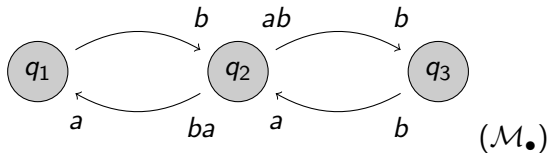
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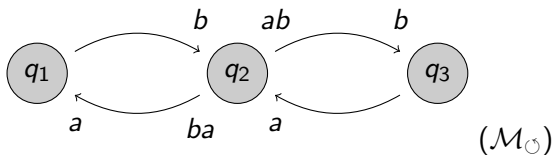
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Undecidability result

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- $S \rightarrow a_1 : q_1(S)$ (**S**), where (q_1, a_1) is the initial configuration,
- $q(x) \rightarrow c : q'(x)$ (**R0**), whenever $\delta_0(q) = (c, q')$,

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- $q(a : y) \rightarrow c : q'(y)$ (**R1**), whenever $\delta_1(q, a) = (c, q')$,
- $q(a : b : z) \rightarrow c : q'(z)$ (**R2**), whenever $\delta_2(q, a, b) = (c, q')$.

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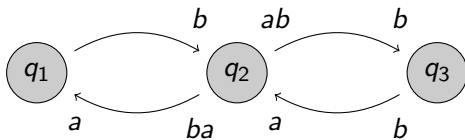
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- $q(a : y) \rightarrow c : q'(y)$ (**R1**), whenever $\delta_1(q, a) = (c, q')$,
- $q(a : b : z) \rightarrow c : q'(z)$ (**R2**), whenever $\delta_2(q, a, b) = (c, q')$.

Theorem

\mathcal{M} halts from the initial configuration iff $S_{\mathcal{M}}$ is not productive for S .

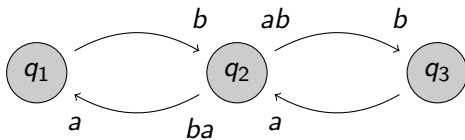
Halts = Not Productive



$$\begin{aligned} \mathbf{S}_{\mathcal{M}.} \quad S \rightarrow a : q_1(S) \quad (1) \quad q_1(x) \rightarrow b : q_2(x) \quad (2) \\ q_3(b : y) \rightarrow a : q_2(y) \quad (3) \quad q_2(a : b : z) \rightarrow b : q_3(z) \quad (4) \\ q_2(b : a : z) \rightarrow a : q_1(z) \quad (5) \end{aligned}$$

$S \rightarrow a : q_1(S) \rightarrow a : b : q_2(S) \rightarrow \dots \rightarrow a : b : q_2(a : b : q_2(S)) \rightarrow$
 $a : b : b : q_3(q_2(S)) \rightarrow \dots \rightarrow a : b : b : a : a : q_1(q_3(S)) \rightarrow$
 $a : b : b : a : a : b : q_2(q_3(S)) \rightarrow a : b : b : a : a : b : q_2(q_3(a : q_1(S)))$

Loops = Productive



$$\begin{aligned} \mathbf{S}_{\mathcal{M}_O} \quad S &\longrightarrow a : q_1(S) \quad \mathbf{(1)} & q_1(x) &\longrightarrow b : q_2(x) \quad \mathbf{(2)} \\ q_3(y) &\longrightarrow a : q_2(y) \quad \mathbf{(3')} & q_2(a : b : z) &\longrightarrow b : q_3(z) \quad \mathbf{(4)} \\ & & q_2(b : a : z) &\longrightarrow a : q_1(z) \quad \mathbf{(5)} \end{aligned}$$

$S \rightarrow a : q_1(S) \rightarrow \dots \rightarrow a : b : b : a : a : b : q_2(q_3(S)) \rightarrow \dots$

$a : b : b : a : a : b : q_2(a : q_2(a : b : q_2(S))) \rightarrow a : b : b : a : a : b : q_2(a : b : q_3(q_2(S)))$

$\rightarrow a : b : b : a : a : b : b : q_3(q_3(q_2(S))) \rightarrow \dots$

Data-oblivious Pure Stream Specification

$$S \rightarrow q(0 : 1 : S)$$

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$$q(1 : \sigma) \rightarrow 1 : 0 : q(\sigma)$$

$$\implies$$

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Non data-oblivious Specification

$$\begin{aligned} S &\rightarrow a : q_1(S) \\ q_1(x) &\rightarrow b : q_2(x) \\ q_3(b : y) &\rightarrow a : q_2(y) \\ q_2(a : b : z) &\rightarrow b : q_3(z) \\ q_2(b : a : z) &\rightarrow a : q_1(z) \end{aligned}$$

 \implies

$$\begin{aligned} S &\rightarrow \bullet : q_1(S) \\ q_1(x) &\rightarrow \bullet : q_2(x) \\ q_3(\bullet : y) &\rightarrow \bullet : q_2(y) \\ q_2(\bullet : \bullet : z) &\rightarrow \bullet : q_3(z) \\ q_2(\bullet : \bullet : z) &\rightarrow \bullet : q_1(z) \end{aligned}$$