# Preorder-Constrained Simulations for Program Refinement with Effects 

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## Today's topic

- a coinductive technique for
quantitative equational reasoning on effectful programs


## Quantitative equational reasoning

- " $p$ behaves the same as $p^{\prime}$
and $p^{\prime}$ terminates with a less number of steps"
- $p \Downarrow^{n} \Longrightarrow p^{\prime} \Downarrow^{m} \wedge n \geq m$
- (basic) quantitative notion of observational refinement


## Quantitative equational reasoning

- " $p$ behaves the same as $p^{\prime}$
and $p^{\prime}$ terminates with a certain number of steps"
- $\left(p \Downarrow^{n} \Longrightarrow p^{\prime} \Downarrow^{m} \wedge n Q m\right) \stackrel{\Delta}{\Longleftrightarrow} p \preceq^{Q} p^{\prime}$ given a "length preorder" $Q \subseteq \mathbb{N} \times \mathbb{N}$
- (basic) quantitative notion of observational refinement


## A coinductive approach

- stepwise reasoning on execution traces, using nondeterministic automata
- e.g. standard simulation
- (FYI: simulation is the asymmetric version of bisimulation)
- $p \preceq^{=} p^{\prime} \stackrel{\Delta}{\Longleftrightarrow}\left(p \Downarrow^{n} \Longrightarrow p^{\prime} \Downarrow^{m} \wedge n=m\right)$
$\Longleftarrow p R p^{\prime}$ such that

$$
\text { (ac) } \underline{-r}_{- \text {(2) }}
$$

(a) Final

(b) Step

## Counting simulation [M. 2020]

- stepwise reasoning on execution traces, using nondeterministic automata
- parameterised by a length preorder $Q \subseteq \mathbb{N} \times \mathbb{N}$
- (FYI: simulation is the asymmetric version of bisimulation)
- $p \leq^{Q} p^{\prime} \stackrel{\Delta}{\Longleftrightarrow}\left(p \Downarrow^{n} \Longrightarrow p^{\prime} \Downarrow^{m} \wedge n Q m\right)$
$\Longleftarrow p R p^{\prime}$ such that

$$
\text { (®) }-\frac{R}{-} \text { (y) }
$$

(a) C-Final

(c) C-Step (2) where $|a w| Q\left|w^{\prime}\right|$

## Counting simulation [M. 2020]

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$\Longleftarrow p R p^{\prime}$ such that

$$
\text { (ac) } \underline{R}^{R} \text { (2) }
$$

(a) C-Final

(c) C-Step (2) where $|a w| Q\left|w^{\prime}\right|$

- soundness only for "deterministic" programs
- or "branching-free" automata


## Counting simulation [M. 2020]

- Today's topic: a coinductive technique for quantitative equational reasoning on effectful programs
- Goal: extend counting simulation to a wider class of effects


Fig. 3: Example pairs of NAs

## Overview

- Goal: extend counting simulation to a wider class of effects
- Challenge 1 :
- Solution 1 :
- Challenge 2 :
- Solution 2 :
- Contribution:


## Challenge 1: varying observation

- $\nabla$ exception

$$
p \leq^{Q} p^{\prime} \stackrel{\Delta}{\Longleftrightarrow}\left(p \Downarrow^{n} \Longrightarrow p^{\prime} \Downarrow^{m} \wedge n Q m\right)
$$

- $\mathbf{X}$ nondeterminism


## result

$p \leq p^{\prime} \Longleftrightarrow\left(p \Downarrow^{n} v \Longrightarrow p^{\prime} \Downarrow^{m} v \wedge n Q m\right)$

- X $\mathrm{I} / \mathrm{O}$
$p \preceq^{Q} p^{\prime} \stackrel{\Delta}{\Longleftrightarrow}\left(p \Downarrow^{n}(v, t r) \Longrightarrow p^{\prime} \Downarrow^{m}(v, t r) \wedge n Q m\right)$


## Challenge 1: varying observation

- internal vs. external choice
- nondeterminism: internal, unobservable choice

$$
\stackrel{\operatorname{or}(1,1)}{\Downarrow 1 \Longrightarrow \underline{1} \Downarrow 1 \wedge 1 \underbrace{=1}_{\text {coincidence of results }}}
$$

- input: external, observable choice

$$
\underline{\operatorname{in}(1,1)} \Downarrow\left(1, \mathrm{in}_{i}\right) \Longrightarrow \underline{1} \Downarrow(1, \varepsilon) \wedge 1=1
$$

coincidence of results, but no coincidence of I/O traces

## Solution 1: "observation preorder" on traces

- program trace $\operatorname{tr} \in \Sigma^{*}$

- examples:
- $\operatorname{Tr}(\operatorname{or}(1,2))=\left\{\right.$ or $_{0} 1$, or $\left._{1} 2\right\}$
- $\operatorname{Tr}(\mathrm{in}(1,2))=\left\{\mathrm{in}_{0} 1, \mathrm{in}_{1} 2\right\}$
- $\operatorname{Tr}(1)=\{1\}$
- $\operatorname{Tr}(1+1)=\{\tau 2\}$


## Solution 1: "observation preorder" on traces

- program trace tr $\in \Sigma^{*}$

- in general: $p_{0} \xrightarrow{l_{0}} p_{1} \xrightarrow{l_{1}} \cdots \xrightarrow{l_{k}} \xrightarrow{n} \boldsymbol{\checkmark}$


## Solution 1: "observation preorder" on traces

- program trace $\operatorname{tr} \in \Sigma^{*}$

- introducing "observation preorder" $\mathbb{Q} \subseteq \Sigma^{*} \times \Sigma^{*}$


## Solution 1: "observation preorder" on traces

- program trace $\operatorname{tr} \in \Sigma^{*}$


## where $\Sigma=\{\tau\} \cup \mathbb{N} \cup \bar{\Omega}$



- introducing "observation preorder" $\mathbb{Q} \subseteq \Sigma^{*} \times \Sigma^{*}$
- e.g. lifted length preorder:

$$
\text { given } Q \subseteq \mathbb{N} \times \mathbb{N}, \quad t \dot{Q} u \stackrel{\Delta}{\Longleftrightarrow}|t| Q|u|
$$

## Solution 1: "observation preorder" on traces

- program trace $\operatorname{tr} \in \Sigma^{*}$
where $\Sigma=\{\tau\} \cup \mathbb{N} \cup \bar{\Omega}$

- introducing "observation preorder" $\mathbb{Q} \subseteq \Sigma^{*} \times \Sigma^{*}$
- e.g. "filtered equality"
given $\Sigma^{\prime} \subseteq \Sigma, \quad t={ }_{\left(\operatorname{rem}_{\Sigma^{\prime}}\right)} u \stackrel{\Delta}{\Longleftrightarrow} t$ and $u$ are the same except for $\Sigma^{\prime}$
- $\tau a b \tau c \tau \tau=\left(\mathrm{rem}_{\{\tau\}} a b c\right.$


## Solution 1: "observation preorder" on traces

- program trace $\operatorname{tr} \in \Sigma^{*}$

- introducing "observation preorder" $\mathbb{Q} \subseteq \Sigma^{*} \times \Sigma^{*}$

Definition 1 ((quantitative) refinement). Let $Q$ be a preorder on $\mathbb{N}$ (dubbed length preorder).

1. For $\Omega_{\mathrm{err}}, t \preceq \preceq_{\mathrm{err}}^{Q} u$ is defined by $\forall w .\left(t \xrightarrow{w} \checkmark \Longrightarrow \exists w^{\prime} \cdot u \xrightarrow{w^{\prime}} \checkmark \wedge|w| Q\left|w^{\prime}\right|\right)$.
2. For $\Omega_{\mathrm{nd}}, t \preceq_{\mathrm{nd}}^{Q} u$ is defined by $\forall w .\left(t \xrightarrow{w} \checkmark \Longrightarrow \exists w^{\prime} \cdot u \xrightarrow{w^{\prime}} \checkmark \wedge|w| Q\left|w^{\prime}\right| \wedge\right.$ $\left.w=\operatorname{rem}_{\{\tau\} \cup \overline{\Omega_{\mathrm{nd}}}} w^{\prime}\right)$.
3. For $\Omega_{\mathrm{io}}, t \preceq_{\mathrm{io}}^{Q} u$ is defined by $\forall w \cdot\left(t \xrightarrow{w} \checkmark \Longrightarrow \exists w^{\prime} \cdot u \xrightarrow{w^{\prime}} \checkmark \wedge|w| Q\left|w^{\prime}\right| \wedge\right.$ $\left.w=\operatorname{rem}_{\{\tau\}} w^{\prime}\right)$.

## Solution 1: "observation preorder" on traces

- program trace $\operatorname{tr} \in \Sigma^{*}$

- introducing "observation preorder" $\mathbb{Q} \subseteq \Sigma^{*} \times \Sigma^{*}$

| $\dot{Q}$ | refinement $\preceq_{\text {err }}^{Q}$ for exception |
| :---: | :---: |
| $\dot{Q} \cap=\operatorname{rem}_{\{\tau\} \cup \overline{\Omega_{n d}}}$ | refinement $\preceq_{\text {nd }}^{Q}$ for nondeterminism |
| $\dot{Q} \cap==_{\text {rem }}^{\{\tau\}}$ | refinement $\preceq_{\mathrm{io}}^{Q}$ for I/O |

## Examples

- exhibit quantitative refinement $\leq_{\text {err }}^{\leq}, \leq_{\text {nd }}^{ \pm}, \leq_{\text {io }}^{\star}$


Fig. 3: Example pairs of NAs

## Overview

- Goal: extend counting simulation to a wider class of effects
- Starting point: $\mathbf{V}$ exception $\mathbf{X}$ nondeterminism $\mathbf{X I / O}$
- Challenge 1 : varying observation
- Solution 1: "observation preorder" on traces
- Challenge 2:
- Solution 2:
- Contribution:


## Challenge 2: branching effects

- $\nabla$ exception
- $\mathbf{X}$ nondeterminism
- X I/O
- unsoundness of counting simulation for branching effects
- due to incomplete inspection of branches



## Solution 2: limited $\exists$

- from unlimited $\exists$ to limited $\exists$

- enabling full inspection of branches


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- Solution 1: "observation preorder" on traces
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- Solution 2: limited $\exists$
- Contribution:


## Contribution: (M, Q)-simulation

- parameterised by
- "look-ahead bound" $M \in \mathbb{N}_{+}$
- observation preorder $\mathbb{Q} \in \Sigma^{*} \times \Sigma^{*}$

Definition 3 (( $M, \mathbf{Q})$-simulations). For each $M \in \mathbb{N}_{+}$, a binary relation $R \subseteq$ $X_{1} \times X_{2}$ is an $M$-bounded $\mathbf{Q}$-constrained simulation ( $(M, \mathbf{Q})$-simulation in short) from $\mathcal{A}_{1}$ to $\mathcal{A}_{2}$ if, for any $(x, y) \in R$, the following Final ${ }^{M}$ and Step ${ }^{M}$ hold.
Final ${ }^{M}$ For each $w=a_{1} \ldots a_{n} \in \Sigma^{*}$ and $x_{1} \ldots x_{n} \in X_{1}^{*}$ such that $n<M$, $x \stackrel{a_{1}}{\sim} x_{1} x_{1} \cdots \stackrel{a_{n}}{\sim} x_{1} x_{n}$ and $x_{n} \in F_{1}$, there exist $w^{\prime} \in \Sigma^{*}$ and $y^{\prime} \in X_{2}$ such that $w \mathbf{Q} w^{\prime}, y \stackrel{w^{\prime}}{\rightsquigarrow_{2}} y^{\prime}$ and $y^{\prime} \in F_{2}$.
 $x_{M}$, there exist $k \in\{1, \ldots, M\}, w^{\prime} \in \Sigma^{*}$ and $y^{\prime} \in X_{2}$ such that $a_{1} \cdots a_{k} \mathbf{Q} w^{\prime}$, $y \stackrel{w^{\prime}}{w_{2}} y^{\prime}$ and $x_{k} R y^{\prime}$.

## Contribution: $(M, \mathbb{Q})$-simulation

- parameterised by
- "look-ahead bound" $M \in \mathbb{N}_{+}$
- observation preorder $\mathbb{Q} \in \Sigma^{*} \times \Sigma^{*}$

Definition 3 (( $M, \mathbf{Q})$-simulations). For each $M \in \mathbb{N}_{+}$, a binary relation $R \subseteq$ $X_{1} \times X_{2}$ is an $M$-bounded $\mathbf{Q}$-constrained simulation ( $M, \mathbf{Q}$ )-simulation in short) from $\mathcal{A}_{1}$ to $\mathcal{A}_{2}$ if, for any $(x, y) \in R$, the following Final ${ }^{M}$ and Step ${ }^{M}$ hold.

(a) Final ${ }^{M}$ where $|w|<M \wedge w \mathbf{Q} w^{\prime}$
(b) Step ${ }^{M}$ where $a_{1} \cdots a_{k} \mathbf{Q} w^{\prime}$

## Contribution: $(M, \mathbb{Q})$-simulation

- parameterised by
- "look-ahead bound" $M \in \mathbb{N}_{+}$
- observation preorder $\mathbb{Q} \in \Sigma^{*} \times \Sigma^{*}$

Corollary 1 (correctness of ( $M, \mathbf{Q}$ )-simulations wrt. refinement).

1. For any $M \in \mathbb{N}_{+}$and $t, u \in \mathbf{T}_{\Omega_{\mathrm{err}}}, t \lesssim_{M, \dot{Q}} u \Longrightarrow t \preceq_{\mathrm{err}}^{Q} u$.
2. For any $M \in \mathbb{N}_{+}$and $t, u \in \mathbf{T}_{\Omega_{\mathrm{nd}}}, t \lesssim_{M, \dot{Q} \cap=\text { rem }_{\{\tau\}} \cup \overline{\Omega_{\mathrm{nd}}}} u \Longrightarrow t \preceq_{\text {nd }}^{Q} u$.
3. For any $M \in \mathbb{N}_{+}$and $t, u \in \mathbf{T}_{\Omega_{\mathrm{i}}}, t \lesssim_{M, \dot{Q} \cap={ }_{\text {rem }}^{\{\tau\}}} u \Longrightarrow t \preceq_{\mathrm{io}}^{Q} u$.

## Examples of $(M, \mathbb{Q})$-simulations

- $(2, \dot{\leq})$-simulation for (a)
- $\left(1, \doteq \cup==_{\operatorname{rem}_{\{\tau\} \cup \bar{\Omega}}}\right)$-simulation for (b)
- $\left(2, \doteq \cup=_{\text {rem }_{\{t]}}\right)$-simulation for (c)

$\begin{array}{ll}\text { (a) } \mathcal{A}_{\Omega_{\mathrm{er}}}(\underline{2} \times(\underline{3}+\underline{4})) \text { and } \mathcal{A}_{\Omega_{\mathrm{err}}}(\underline{2} \times & \text { (b) } \underset{\mathcal{A}_{\Omega_{\mathrm{nd}}}(\operatorname{or}(\underline{1}, \underline{0}))}{\mathcal{A}_{\mathrm{n}_{\mathrm{nd}}}(\operatorname{or}(\underline{1}, \underline{1}))} \\ \underline{3}+\underline{2} \times \underline{4}) & \text { and }\end{array}$

(c) $\mathcal{A}_{\Omega_{\mathrm{io}}}(\underline{1}+\underline{2}+\operatorname{in}(\underline{0}, \underline{1}))$ and $\mathcal{A}_{\Omega_{\mathrm{io}}}(\operatorname{in}(\underline{1}+\underline{2}+\underline{0}, \underline{1}+\underline{2}+\underline{1}))$

Fig. 3: Example pairs of NAs

## Overview

- Goal: extend counting simulation to a wider class of effects
- Starting point: $\boldsymbol{\nabla}$ exception $\mathbf{X}$ nondeterminism $\mathbf{X I / O}$
- Challenge 1: varying observation
- Solution 1: "observation preorder" on traces
- Challenge 2: branching effects
- Solution 2: limited $\exists$
- Contribution: (M, Q)-simulation
- Result: $\sqrt{ }$ exception $\nabla$ nondeterminism $\nabla$ I/O


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- Contribution: a generative spectrum of (M, Q)-simulations
- Result: $\sqrt{ }$ exception $\sqrt{ }$ nondeterminism $\sqrt{ }$ I/O


## A generative spectrum of $(M, \mathbb{Q})$-simulations



Fig. 1: A generative spectrum, parameterised by the observation preorder $\mathbf{Q}$

| observation preorder Q | (1, $\mathbf{Q}$ )-simulation | Q-trace inclusion $\sqsubseteq_{\text {Q }}$ |
| :---: | :---: | :---: |
| $=$ | standard simulation | finite trace inclusion |
| $=\operatorname{rem}_{\{\tau\}}$ | weak simulation | weak trace inclusion |
| $\dot{Q}$ |  | refinement $\preceq_{\text {err }}^{Q}$ for exception |
| $\dot{Q} \cap=\operatorname{rem}_{\{\tau\} \cup \overline{\Omega_{\mathrm{nd}}}}$ | (new instances) | refinement $\preceq_{\text {nd }}^{Q}$ for nondeterminism |
| $\dot{Q} \cap=\operatorname{rem}_{\{\tau\}}$ |  | refinement $\preceq_{i o}^{Q}$ for I/O |

Table 1: Instances of the two ends of the generative spectrum (see Sec. 4 for details)

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## Future work 1: bunching branches

- X probabilistic choice
- a naive attempt yields a false refinement:

$$
\operatorname{or}_{0.5}(1,1) \sqsubseteq_{\leq_{+}} \operatorname{or}_{0.5}(0,1)
$$

- Idea: from nondeterministic automata to weighted automata?


## Future work 2: efficient solving

- $p \stackrel{?}{\leq^{Q}} p^{\prime} \Longleftarrow p \lesssim_{M, Q} p^{\prime}$ for nondeterministic automata $\mathscr{A}(p), \mathscr{A}\left(p^{\prime}\right)$ that represent whole execution of $p, p^{\prime}$
$\Longleftarrow$ reachability in a graph "pairing" $\mathscr{A}(p)$ with $\mathscr{A}\left(p^{\prime}\right)$
- polynomial time solving, based on whole execution :)
- Idea: solving without executing programs
- using TRS techniques? [M. \& Hamana, FLOPS '24]


## Overview

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- Challenge 1: varying observation
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- Challenge 2: branching effects
- Solution 2: limited $\exists$
- Contribution: a generative spectrum of (M, Q)-simulations
- Result: $\nabla$ exception $\nabla$ nondeterminism $\nabla$ I/O
- (with a game-theoretic characterisation)
- (with the up-to technique)

