# Preorder-Constrained Simulations for Program Refinement with Effects

#### <u>Koko Muroya</u> (RIMS, Kyoto University)

Takahiro Sanada (RIMS, Kyoto University)

Natsuki Urabe (NII)

# Today's topic

• a coinductive technique for

quantitative equational reasoning on effectful programs

## Quantitative equational reasoning

• "p behaves the same as p'

and p' terminates with a less number of steps"

• 
$$p \Downarrow^n \implies p' \Downarrow^m \land n \ge m$$

• (basic) quantitative notion of observational refinement

## Quantitative equational reasoning

• "p behaves the same as p'

and p' terminates with a certain number of steps"

• 
$$(p \Downarrow^n \Longrightarrow p' \Downarrow^m \land n Q m) \stackrel{\Delta}{\iff} p \preceq^Q p'$$
  
given a "length preorder"  $Q \subseteq \mathbb{N} \times \mathbb{N}$ 

• (basic) quantitative notion of observational refinement

## A coinductive approach

- stepwise reasoning on execution traces, using nondeterministic automata
- e.g. standard simulation
  - (FYI: simulation is the asymmetric version of bisimulation)

• 
$$p \leq p' \Leftrightarrow (p \Downarrow^n \Longrightarrow p' \Downarrow^m \land n = m)$$
  
 $\iff p R p'$  such that

$$x - \frac{R}{-y}$$





(b) Step

# Counting simulation [M. 2020]

- stepwise reasoning on execution traces, using nondeterministic automata
- parameterised by a length preorder  $Q \subseteq \mathbb{N} \times \mathbb{N}$ 
  - (FYI: simulation is the asymmetric version of bisimulation)

• 
$$p \leq^{Q} p' \quad \stackrel{\Delta}{\iff} \quad (p \Downarrow^{n} \implies p' \Downarrow^{m} \land n Q m)$$
  
 $\iff p R p' \text{ such that}$ 

 $x - \frac{R}{y}$ 

(a) C-Final

# Counting simulation [M. 2020]

stepwise reasoning on execution traces, using nondeterministic automata

• 
$$p \leq^{Q} p' \quad \stackrel{\Delta}{\Leftrightarrow} \quad (p \Downarrow^{n} \Longrightarrow p' \Downarrow^{m} \land n Q m)$$
  
 $\leftarrow p R p' \text{ such that}$   
 $\stackrel{x'}{=} \stackrel{R}{=} \stackrel{y}{y}$   
(a) *C-Final*  
(c) *C-Step* (2) where  $|aw|Q|w'|$ 

- soundness only for "deterministic" programs
  - or "branching-free" automata

# Counting simulation [M. 2020]

- Today's topic: a coinductive technique for quantitative equational reasoning on effectful programs
- Goal: extend counting simulation to a wider class of effects



Fig. 3: Example pairs of NAs

• Goal: extend counting simulation to a wider class of effects

- Challenge 1:
  - Solution 1:
- Challenge 2:
  - Solution 2:
- Contribution:

# Challenge 1: varying observation

• exception  

$$p \leq^{Q} p' \stackrel{\Delta}{\Leftrightarrow} (p \downarrow^{n} \Rightarrow p' \downarrow^{m} \land n Q m)$$
  
•  $\bigstar$  nondeterminism  
 $p \leq^{Q} p' \stackrel{\Delta}{\Leftrightarrow} (p \downarrow^{n} v \Rightarrow p' \downarrow^{m} v \land n Q m)$   
•  $\bigstar I/O$   
 $p \leq^{Q} p' \stackrel{\Delta}{\Leftrightarrow} (p \downarrow^{n} (v, tr) \Rightarrow p' \downarrow^{m} (v, tr) \land n Q m)$ 

# Challenge 1: varying observation

- internal vs. external choice
  - nondeterminism: internal, unobservable choice

$$or(1,1) \Downarrow 1 \implies 1 \Downarrow 1 \land 1 = 1$$

$$coincidence of results$$

• input: external, observable choice

$$\underline{\operatorname{in}(1,1)} \Downarrow (1,\operatorname{in}_i) \Longrightarrow \underline{1} \Downarrow (1,\varepsilon) \land 1 = 1$$

coincidence of results, but no coincidence of I/O traces

• program trace  $tr \in \Sigma^*$ 



- examples:
  - $Tr(or(1,2)) = \{or_01, or_12\}$
  - $Tr(in(1,2)) = \{in_01, in_12\}$
  - $Tr(1) = \{1\}$
  - $\operatorname{Tr}(1+1) = \{\tau 2\}$

• program trace  $tr \in \Sigma^*$ 



• in general:  $p_0 \xrightarrow{l_0} p_1 \xrightarrow{l_1} \cdots \xrightarrow{l_k} \underline{n} \xrightarrow{n} \checkmark$ 

• program trace  $tr \in \Sigma^*$ 



• introducing "observation preorder"  $\mathcal{Q} \subseteq \Sigma^* \times \Sigma^*$ 

• program trace  $tr \in \Sigma^*$ 



- introducing "observation preorder"  $\mathcal{Q} \subseteq \Sigma^* \times \Sigma^*$
- e.g. lifted length preorder:

given 
$$Q \subseteq \mathbb{N} \times \mathbb{N}$$
,  $t \dot{Q} u \iff |t| Q |u|$ 

• program trace  $tr \in \Sigma^*$ 



- introducing "observation preorder"  $\mathcal{Q} \subseteq \Sigma^* \times \Sigma^*$
- e.g. "filtered equality"

given  $\Sigma' \subseteq \Sigma$ ,  $t =_{(\operatorname{rem}_{\Sigma'})} u \iff t$  and u are the same except for  $\Sigma'$ 

• 
$$\tau ab\tau c\tau\tau =_{(\operatorname{rem}_{\{\tau\}})} abc$$

• program trace  $tr \in \Sigma^*$ 



• introducing "observation preorder"  $\mathcal{Q} \subseteq \Sigma^* \times \Sigma^*$ 

**Definition 1 ((quantitative) refinement).** Let Q be a preorder on  $\mathbb{N}$  (dubbed length preorder).

1. For 
$$\Omega_{\text{err}}$$
,  $t \leq_{\text{err}}^{Q} u$  is defined by  $\forall w.(t \xrightarrow{w} \checkmark) \Longrightarrow \exists w'.u \xrightarrow{w'} \checkmark \land |w|Q|w'|).$ 

- 2. For  $\Omega_{nd}$ ,  $t \preceq^Q_{nd} u$  is defined by  $\forall w.(t \xrightarrow{w} \checkmark) \implies \exists w'.u \xrightarrow{w} \checkmark \land |w|Q|w'| \land w =_{\operatorname{rem}_{\{\tau\} \cup \overline{\Omega_{nd}}} w').$
- 3. For  $\Omega_{io}$ ,  $t \preceq^{Q}_{io} u$  is defined by  $\forall w.(t \xrightarrow{w} \checkmark) \implies \exists w'.u \xrightarrow{w'} \checkmark \land |w|Q|w'| \land w =_{\mathsf{rem}_{\{\tau\}}} w').$

• program trace  $tr \in \Sigma^*$ 



• introducing "observation preorder"  $\mathcal{Q} \subseteq \Sigma^* \times \Sigma^*$ 



#### **Examples**

• exhibit quantitative refinement  $\leq_{err}^{\leq}, \leq_{nd}^{=}, \leq_{io}^{=}$ 



Fig. 3: Example pairs of NAs

- Goal: extend counting simulation to a wider class of effects
  - Starting point:  $\mathbf{V}$  exception  $\mathbf{X}$  nondeterminism  $\mathbf{X}$  I/O

- Challenge 1: varying observation
  - Solution 1: "observation preorder" on traces
- Challenge 2:
  - Solution 2:
- Contribution:

# Challenge 2: branching effects

- exception
- 🗙 nondeterminism



- unsoundness of counting simulation for branching effects
  - due to incomplete inspection of branches



# Solution 2: limited $\exists$

• from unlimited  $\exists$  to limited  $\exists$ 



• enabling full inspection of branches

- Goal: extend counting simulation to a wider class of effects

- Challenge 1: varying observation
  - Solution 1: "observation preorder" on traces
- Challenge 2: branching effects
  - Solution 2: limited  $\exists$
- Contribution:

# Contribution: $(M, \mathcal{Q})$ -simulation

- parameterised by
  - "look-ahead bound"  $M \in \mathbb{N}_+$
  - observation preorder  $\mathcal{Q} \in \Sigma^* \times \Sigma^*$

**Definition 3** ((M, Q)-simulations). For each  $M \in \mathbb{N}_+$ , a binary relation  $R \subseteq X_1 \times X_2$  is an M-bounded Q-constrained simulation ((M, Q)-simulation in short) from  $\mathcal{A}_1$  to  $\mathcal{A}_2$  if, for any  $(x, y) \in R$ , the following Final<sup>M</sup> and Step<sup>M</sup> hold.

**Final**<sup>M</sup> For each  $w = a_1 \dots a_n \in \Sigma^*$  and  $x_1 \dots x_n \in X_1^*$  such that n < M,  $x \stackrel{a_1}{\rightsquigarrow} x_1 \dots \stackrel{a_n}{\rightsquigarrow} x_n$  and  $x_n \in F_1$ , there exist  $w' \in \Sigma^*$  and  $y' \in X_2$  such that  $w \mathbf{Q} w', y \stackrel{w'}{\rightsquigarrow} y' = y'$  and  $y' \in F_2$ . **Step**<sup>M</sup> For each  $a_1 \dots a_M \in \Sigma^M$  and  $x_1 \dots x_M \in X_1^M$  such that  $x \stackrel{a_1}{\rightsquigarrow} x_1 \dots \stackrel{a_M}{\rightsquigarrow} x_M$ , there exist  $k \in \{1, \dots, M\}, w' \in \Sigma^*$  and  $y' \in X_2$  such that  $a_1 \dots a_k \mathbf{Q} w', y \stackrel{w'}{\rightsquigarrow} y' \stackrel{w'}{\rightsquigarrow} y' = y'$  and  $x_k Ry'$ .

# Contribution: $(M, \mathcal{Q})$ -simulation

- parameterised by
  - "look-ahead bound"  $M \in \mathbb{N}_+$
  - observation preorder  $\mathcal{Q} \in \Sigma^* \times \Sigma^*$

**Definition 3** ((M, Q)-simulations). For each  $M \in \mathbb{N}_+$ , a binary relation  $R \subseteq X_1 \times X_2$  is an M-bounded Q-constrained simulation ((M, Q)-simulation in short) from  $\mathcal{A}_1$  to  $\mathcal{A}_2$  if, for any  $(x, y) \in R$ , the following Final<sup>M</sup> and Step<sup>M</sup> hold.



# Contribution: $(M, \mathcal{Q})$ -simulation

- parameterised by
  - "look-ahead bound"  $M \in \mathbb{N}_+$
  - observation preorder  $\mathcal{Q} \in \Sigma^* \times \Sigma^*$

Corollary 1 (correctness of  $(M, \mathbf{Q})$ -simulations wrt. refinement).

1. For any 
$$M \in \mathbb{N}_+$$
 and  $t, u \in \mathbf{T}_{\Omega_{err}}, t \lesssim_{M,\dot{Q}} u \implies t \preceq^Q_{err} u$ .  
2. For any  $M \in \mathbb{N}_+$  and  $t, u \in \mathbf{T}_{\Omega_{nd}}, t \lesssim_{M,\dot{Q}\cap =_{\operatorname{rem}_{\{\tau\}}\cup\overline{\Omega_{nd}}} u \implies t \preceq^Q_{nd} u$ .  
3. For any  $M \in \mathbb{N}_+$  and  $t, u \in \mathbf{T}_{\Omega_{io}}, t \lesssim_{M,\dot{Q}\cap =_{\operatorname{rem}_{\{\tau\}}}} u \implies t \preceq^Q_{io} u$ .

# Examples of $(M, \mathcal{Q})$ -simulations

•  $(2, \leq)$ -simulation for (a)

•  $(1, \doteq \cup =_{\operatorname{rem}_{\{\tau\}\cup\overline{\Omega}}})$ -simulation for (b)



Fig. 3: Example pairs of NAs

- Goal: extend counting simulation to a wider class of effects
  - Starting point: 🔽 exception 🗙 nondeterminism 🗙 I/O

- Challenge 1: varying observation
  - Solution 1: "observation preorder" on traces
- Challenge 2: branching effects
  - Solution 2: limited  $\exists$
- Contribution: (M, Q)-simulation
  - Result: 🔽 exception 🔽 nondeterminism 🔽 I/O

- Goal: extend counting simulation to a wider class of effects
  - Starting point: 🔽 exception 🗙 nondeterminism 🗙 I/O

- Challenge 1: varying observation
  - Solution 1: "observation preorder" on traces
- Challenge 2: branching effects
  - Solution 2: limited  $\exists$
- Contribution: a *generative spectrum* of (M, Q)-simulations
  - Result: exception nondeterminism I/O

## A generative spectrum of (M, Q)-simulations

$$\begin{array}{ccc} (1, \mathbf{Q}) \text{-similarity} \\ \lesssim_{1, \mathbf{Q}} \end{array} & \longrightarrow & \begin{array}{c} (2, \mathbf{Q}) \text{-similarity} \\ \lesssim_{2, \mathbf{Q}} \end{array} & \longrightarrow & \longrightarrow & \begin{array}{c} \mathbf{Q} \text{-trace inclusion} \\ \sqsubseteq_{\mathbf{Q}} \end{array}$$

Fig. 1: A generative spectrum, parameterised by the observation preorder  $\mathbf{Q}$ 

observation preorder ${\bf Q}$	$(1, \mathbf{Q})$ -simulation	$\mathbf{Q}$ -trace inclusion $\sqsubseteq_{\mathbf{Q}}$
=	standard simulation	finite trace inclusion
$=_{rem_{\{\tau\}}}$	weak simulation	weak trace inclusion
Q		refinement $\preceq^Q_{err}$ for exception
$\dot{Q} \cap =_{rem_{\{\tau\} \cup \overline{\Omega_{red}}}}$	(new instances)	refinement $\preceq^Q_{nd}$ for nondeterminism
$\dot{Q} \cap =_{rem_{\{\tau\}}}$		refinement $\preceq^Q_{\sf io}$ for I/O

Table 1: Instances of the two ends of the generative spectrum (see Sec. 4 for details)

- Goal: extend counting simulation to a wider class of effects
  - Starting point: 🔽 exception 🗙 nondeterminism 🗙 I/O

- Challenge 1: varying observation
  - Solution 1: "observation preorder" on traces
- Challenge 2: branching effects
  - Solution 2: limited  $\exists$
- Contribution: a *generative spectrum* of (M, Q)-simulations
  - Result: exception nondeterminism I/O

## Future work 1: bunching branches

- X probabilistic choice
  - a naive attempt yields a false refinement:

 $or_{0.5}(1,1) \sqsubseteq_{\leq_+} or_{0.5}(0,1)$ 

• Idea: from nondeterministic automata to weighted automata?

## Future work 2: efficient solving

•  $p \leq^{?} p' \iff p \leq_{M, Q} p'$  for nondeterministic automata  $\mathscr{A}(p), \mathscr{A}(p')$ 

that represent whole execution of p, p'

 $\Leftarrow$  reachability in a graph "pairing"  $\mathscr{A}(p)$  with  $\mathscr{A}(p')$ 

- polynomial time solving, based on whole execution
  - Idea: solving without executing programs
    - using TRS techniques? [M. & Hamana, FLOPS '24]

- Goal: extend counting simulation to a wider class of effects
  - Starting point:  $\checkmark$  exception  $\thickapprox$  nondeterminism  $\bigstar$  I/O

- Challenge 1: varying observation
  - Solution 1: "observation preorder" on traces
- Challenge 2: branching effects
  - Solution 2: limited  $\exists$
- Contribution: a *generative spectrum* of (M, Q)-simulations
  - Result: 🗸 exception 🗸 nondeterminism 🗸 I/O
  - (with a game-theoretic characterisation)
  - (with the up-to technique)